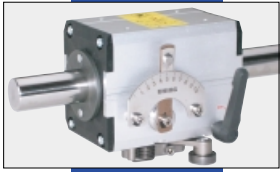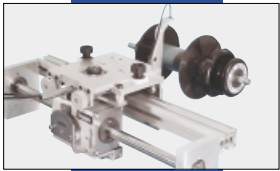# Uhing-Linear Drives ®

Linear Drive Nut RS

...made by

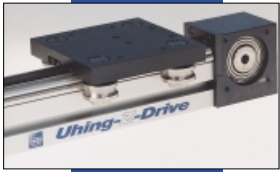UHING ®

Rolling Ring Drives:
Catalog RG/RGK/KI

Non Contact Flange
Detecting System:
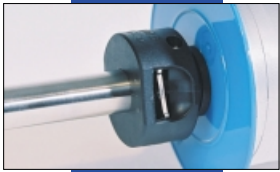Catalog FA

Guide System:
Catalog GS
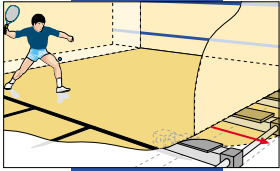
Linear Drive Nut:
Catalog RS

Timing Belt Drive:
Catalog AZ

Fast Action Clamping
System Uhing-easylock®:
Catalog UE

Smooth Shaft Fastener
U-Clip:
Catalog UE

Engineering:
Catalog EG

Automatic Winding
Width Control:
Catalog AVS

Joachim Uhing KG
GmbH & Co. - the originator
of the Rolling Ring Principle
- successful for over 50 years.

More about us at:
www.uhing.com

Our worldwide network of
agencies guarantees a
reliable service on the spot.

Summary of contents

Uhing - Linear Drive Nut

The Actuator for:
- Linear Motion Drives
- Measurement and
  Inspection Technology
- Materials Handling Systems
- Control Systems
- Medical Engineering

Uhing-Linear Drive Nuts (RS) are
non-positive drives which convert
the rotation of a plain round
shaft into linear motion.
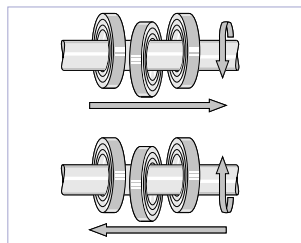
Principle of operation

The effect is achieved by pres-
sing specially crowned Rolling
Rings against the shaft and
allowing them to roll on the
surface of the shaft at an angle
which determins their pitch.

UHING®

With permission of Zeiss

With permission of Zoller

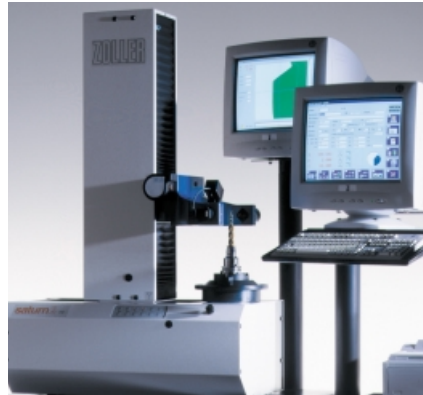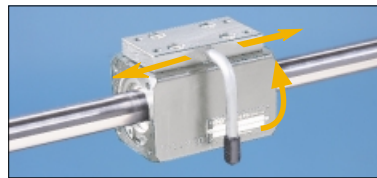With permission of
DMG Microset GmbH

Characteristics

- Backlash-free
- Resistant to vibrations
- Compact design
- Overload protection
- High-efficiency
- Quiet in operation
- Low maintenance
- Free-movement lever
- Good sealing possibilities
- Linked nuts
  for higher side thrust
- Left- and right-hand pitch on
  the same shaft

free-movement lever

linked nuts
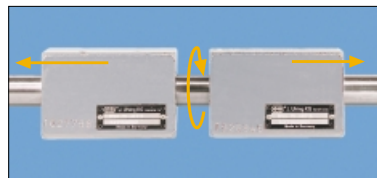
left- and right hand pitch
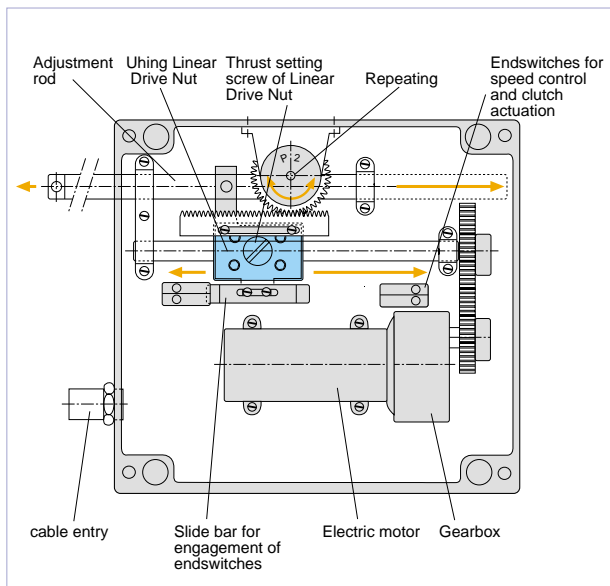
Setting unit for speed control of ship motors

Adjustment rod
Uhing Linear Drive Nut
Thrust setting screw of Linear Drive Nut
Repeating
Endswitches for speed control and clutch actuation
cable entry
Slide bar for engagement of endswitches
Electric motor
Gearbox
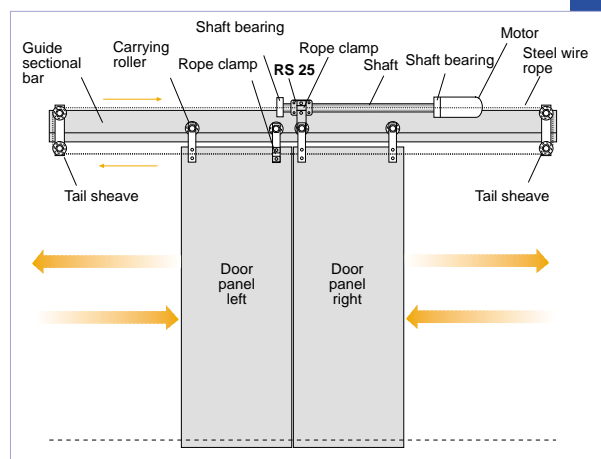
Drive for double sliding doors

Guide sectional bar
Carrying roller
Rope clamp
Shaft bearing
Rope clamp
RS 25
Shaft
Shaft bearing
Motor
Steel wire rope
Tail sheave
Tail sheave
Door panel left
Door panel right
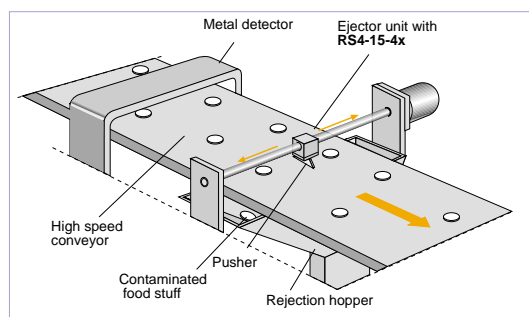
Ejector unit for contaminated foodstuffs

Metal detector
Ejector unit with RS4-15-4x
High speed conveyor
Pusher
Contaminated food stuff
Rejection hopper

UHING ®

Dimensions and Technical Details

Uhing - Linear Drive Nut
Types RS

Types RS

Special design for open Linear Drive Nuts upon request

max. screw depth

The CAD - drawings and technical details are available in the Internet.

Dimensions

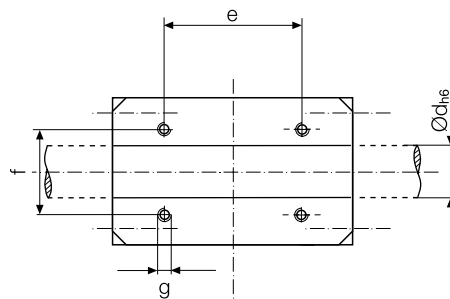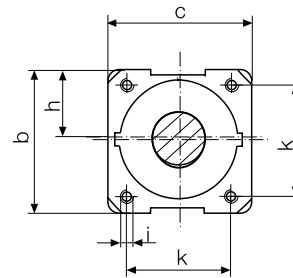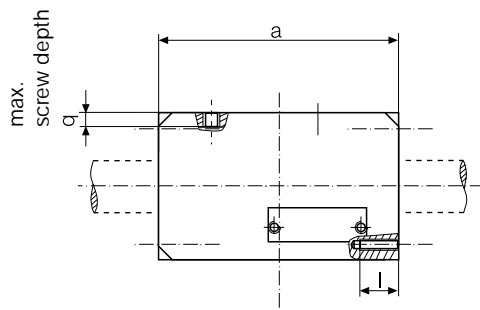| Type	Weight m (kg)	a*	a₁*	b	c	d_{h6}	e	f	g	h ±0.3	i	k	l	q	F_{RS}(N)	M_0(Ncm)	h(mm)
				Dimensions for **RS** Typen (mm)											Technical Details		
RS3-10-4	0,14	47	65	35	35	10	30	18	M 4	17,3	M 3	26	6	5	100	1,8	5,0
RS4-10-4	0,18	55	73	"	"	"	"	"	"	"	"	"	"	"	200	5,0	"
RS4-15-4	0,23	62	82	40	40	15	26	18	M 4	19,6	M 4	30	8	5	260	5,0	7,5
RS4-20-4	0,55	83	108	52	52	20	40	30	M 5	26	M 5	40	11	8	420	10,0	10,0
RS4-25-4	0,70	85	110	60	60	25	40	30	M 5	29,4	M 5	45	10	9	600	20,0	12,5
RS4-35-4	1,55	105	126	80	80	35	50	40	M 6	40	M 6	60	12	13	900	45,0	17,5
RS4-50-3	2,70	120	140	100	100	50	50	50	M 8	48,8	-	-	-	16	1300	140,0	25,0
RS4-60-3	4,20	130	156	120	120	60	69	62	M10	58,4	-	-	-	15	2000	200,0	30,0

Heavy print:
standard versions

*Attention:
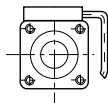If wipers are used, dimension a becomes a_1.

F_{RS} (N) = Maximum available side thrust
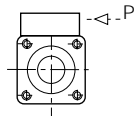M_0 (Ncm) = Idling torque
h (mm) = Maximum pitch

Features

F Free-Movement Lever, mechanical

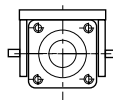when operated, the nut can be slide freely along the shaft

P Free-Movement Lever, pneumatical

as above, operated with a pressure of p = 6 bar
Attention: Units supplied with **P** have a reduced thrust. Refer to supplier for details

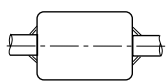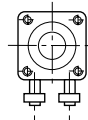### Adapter

for twist free coupling system

Wipers

for sealing between nut and shaft (to +70°C)
Attention! For units with wipers please note dimension a_1 on page 4.

R Steady Rollers

Rolls on Linear Drive Nut (in conjunction with a guide bar) prevent the rotation of the nut on the shaft.

Details of other types upon request.

Product Survey
(Type designation chart)

Product group	Uhing Linear Drive Nut						
Type reference	RS						
Style (Number of Rolling Rings)	**3** o. 4	3 or **4**					
Size (Shaft diameter)	**10**	**15**	**20**	**25**	**35**	50	60
Design category	4	4	4	4	4	3	3
Pitch direction	**L** (= left), **R** (= right)						
Pitch max.	0,1 · 0,2 · 0,3 · 0,4 · **0,5** x shaft Ø						
Available features[1]	F, P, R						
Customer specific features[2]	X						

Heavy print: standard versions

[1] Available features

Free Movement Lever
F mechanical
P pneumatical
R Steady Rollers

[2] Customer specific features

- Adapter
- Wipers
- Felt rings
- Increased protection against corrosion
- Specific pitch
- Grease nipples
- Reduced thrust

Ordering specifications / Example

Type reference	RS	4	25	4	R	12.5	P	X
Style		●						
Size (shaft dia.) Separator symbols			●					
Design category				●				
Pitch direction					●			
Pitch						●		
Available features							●	
Customer specific features								●

Selection

If you wish Joachim Uhing KG GmbH & Co. to make selection for you in respect of your application, please ask for Applications Questionnaire 03e.

Formulae and related units

d(mm)	= shaft diameter
F(N)	= side thrust required
F_{RS}(N)	= side thrust produced by Linear Drive Nut type RS
F_R(N)	= force of friction ($F_N \cdot \mu$) only relevant when the associated mass is mounted on its own independent carriage
F_N(N)	= normal force of total weight of associated mass and carriage

μ	= coefficient of friction
F_Z(N)	= additional force e. g. component of the cutting force of a separator
f(mm)	= shaft sag from diagram
g(m/s²)	= acceleration due to gravity (9.81 m/s²). Note: for horizontal applications $m \cdot g = 0$
h(mm)	= Drive Nut pitch (travel per shaft revolution)
l(mm)	= length of shaft between centre of bearing brackets
m(kg)	= total mass to be moved, including Drive Nut, connections etc.

M_d (Ncm)	= drive torque
M_o (Ncm)	= idling torque
n(r.p.m.)	= shaft speed
n_{crit}(r.p.m.)	= critical shaft speed
P(kW)	= drive power required
t(s)	= acceleration or braking time
v(m/sec)	= maximum speed of travel
C(N)	= dynamic loading of Rolling Rings
P_R(N)	= radial loading of Rolling Rings

1. Side thrust

$$F = 2 \left(\frac{m \cdot v}{t} + m \cdot g \right) + F_R + F_Z$$

A Drive Nut should be selected which has a greater side thrust than the value calculated.

$$F < F_{RS}$$

Several smaller Drive Nuts can be coupled together if available space so dictates. The total thrust available is the sum of the individual values.

2. Shaft speed

$$n = \frac{v \cdot 6 \cdot 10^4}{h_{max}}$$

2.1. Max. shaft speed
RS 3-10-4 = 10000 min⁻¹
RS 4-15-4 = 8000 min⁻¹
RS 4-20-4 = 7000 min⁻¹
RS 4-25-4 = 6000 min⁻¹
RS 4-35-4 = 4000 min⁻¹
RS 4-50-3 = 3400 min⁻¹
RS 4-60-3 = 2500 min⁻¹

2.2 Critical shaft speed

$$n_{crit} = 1{,}225 \cdot 10^8 \frac{d}{l^2}$$

Note
Depending upon its quality, the shaft can go out of balance at a speed of up to 25 % lower than that specified above.
If it is necessary to go through a critical range in order to reach the operational speed, this can lead to short term shaft vibration. This has no effect on the operation of the Drive Nut.
If the operational speed is in the critical speed range, this can be rectified as follows:
1. with a double bearing support at one end, increase factor approx. 1,5.
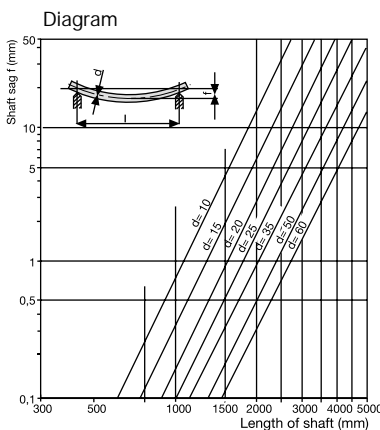2. with double bearing supports at both ends, increase factor approx. 2,2.

The distance between the bearing support brackets should be at least 2.5 x the diameter of the shaft.

3. Drive torque

$$M_d = \frac{F_{RS} \cdot h}{20 \cdot \pi} + M_O$$

Values for M_o to be taken from the technical detail tables.

4. Shaft sag

Diagram

Shaft sag f (mm) vs Length of shaft (mm)

5. Calculation of the operational life of Rolling Rings

1. Select C

Typ	C(N)
RS 10	4620
RS 15	5590
RS 20	9360
RS 25	11200
RS 35	15900
RS 50	21600
RS 60	29600

2. Calculate P_R
RS 10   : $P_R = 5 \cdot F_{RS}$*
RS 15 - 60 : $P_R = 2{,}5 \cdot F_{RS}$*

*F = calculated value of the side thrust according to 1. only if increasing of operational life time of the rolling rings is really necessary. In case of order it is an absolute must to mention.
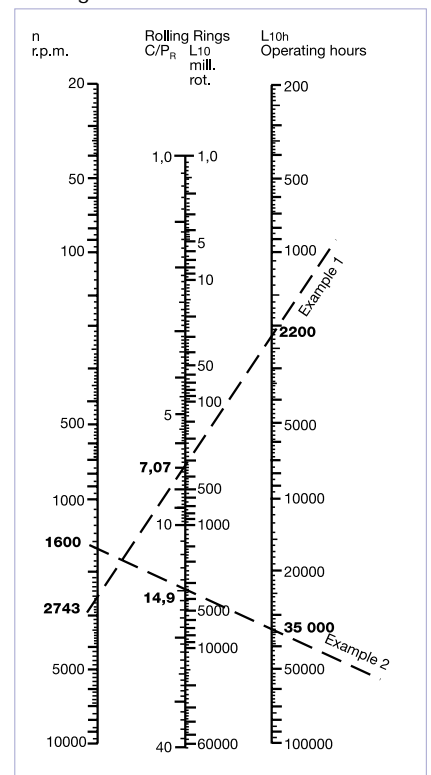
3. Divide C by P_R
4. Calculate the required shaft speed

$$n = \frac{v \cdot 6 \cdot 10^4}{h_{max}}$$

5. Determine the operational life in hours from the nomogram

Example 1	Example 2
RS4-35-4R17,5 speed 0,8 m/s	RS4-15-4R7,5 **reduced side thrust 150 N** speed 0,2 m/s
1. C = 15900	C = 5590
2. P_R = 2,5 · 900 N = 2250 N	P_R = 2,5 · 150 N = 375 N
3. $\frac{C}{P_R} = \frac{15900}{2250} = 7{,}07$	$\frac{C}{P_R} = \frac{5590}{375} = 14{,}9$
4. n = $\frac{0{,}8 \cdot 6 \cdot 10^4}{17{,}5}$ = 2743 r.p.m.	n = $\frac{0{,}2 \cdot 6 \cdot 10^4}{7{,}5}$ = 1600 r.p.m.
5. L_{10h} = 2200 operating hours	L_{10h} = 35000 operating hours

Nomogram

UHING®

INDUSTRIAL **Magza** ®
DIST. AUTORIZADO

MEX (55) 53 63 23 31   MTY (81) 83 54 10 18
QRO (442) 1 95 72 60   ventas@industrialmagza.com

1. Shaft material

1.1. Basic requirements
Uhing Linear Drives should only be used in conjunction with steel shafts manufactured from induction surface hardened, ground and finished bar of the following quality, minimum:
- surface hardness: 50 HRC
- tolerance on diameter: h6
- out of roundness: maximum one half of the diameter variation permitted by ISO tolerance h6
- true running tolerance (DIN ISO 1101): ≤ 0,1 mm/m

1.2. Uhing - precision shaft
Standard:
Material Cf 53, Mat.-Nr. 1.1213, induction surface hardened, 60-64 HRC

Rust resistant:
Material X 40 Cr 13, Mat.-Nr. 1.4034, induction surface hardened, 51-55 HRC

Rust and acid resistant:
Material X 90 CrMoV 18, Mat.-Nr. 1.4112, induction surface hardened, 52-56 HRC

- all ground and superfinished
- surface roughness: mean value (DIN 4768 T.1) R_a:≤ 0.35 µm
- tolerance on diameter: h6
- out of roundness: maximum one half of the diameter variation permitted by ISO tolerance h6
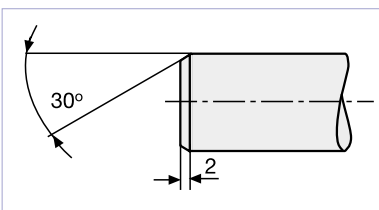- true running tolerance (DIN ISO 1101): ≤ 0.1 mm/m

1.3. Uhing precision shafts with enhanced true running tolerance
Available in the above styles, but
- true running tolerance (DIN ISO 1101): ≤0.03 mm/m

1.4. Leading end chamfer
The leading end of the shaft should be chamfered to avoid damage to the Rolling Rings when screwing the unit onto the shaft.


2. Pitch

The standard pitch is 0,5 x d. This can be ordered for RS as either a right- or a left-handed pitch.
Unless otherwise specified, units having a right-handed pitch will be supplied. For RS subsequent alterations to the pitch are possible with units having a design category -4 reference by changing the associated pitch control wedges.
Non-standard pitches 0,1 - 0,2 - 0,3 and 0,4 x d are available. In this version reduction of the side thrust is recommended to improve the smooth running.

3. Separately carried loads

If Uhing Linear Drive Nuts are used to move separately carried loads, allowance should be made in the coupling to compensate for any misalignment between the drive
shaft and the carriage. The available side thrust will otherwise be affected. If the application so permits, we recommend the use of our twist-free coupling system.

self-aligning coupling
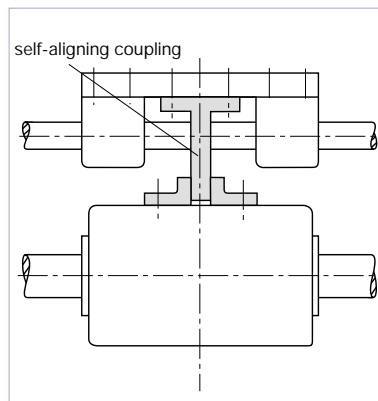
Torque-free coupling system
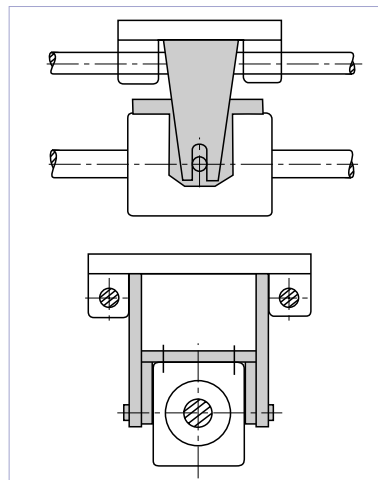
4. Vertical applications

For vertical applications we advise the use of a directly braked motor so as to avoid the possibility of the shaft rotating backwards and the Drive Nut falling due to the high efficiency of the drive. Depending upon the application (safety considerations and value of the installation) a reserve of side thrust should be built in (using a second Drive Nut).

With units having a free-movement lever, care must be taken before its operation to ensure that they are unable to drop in an uncontrolled manner - danger of injury!

5. Temperature range

Uhing Linear Drive Nuts are suitable for operation at temperatures from -10°C to +70°C.
Please enquire for other temperatures.

6. Maintenance

For the lubrication of the shaft, commercially available **MoS2-free ball-bearing greases** can be used, e. g. SKF Alfalub LGMT2, Shell Alvania R2 or G2, Esso Beacon 2, BP Energrease LS2.
Procedure:
Clean the shaft and spread the grease as thinly as possible with a rag.
Frequency:
Once every ten weeks.

7. Symmetry

The maximum difference in pitch for the two directions of travel is 2 %. We therefore recommend the use of positional sensors for positioning applications.

We reserve the right to make technical alterations.

For further information please refer to our Operating Instructions 05e, available on request or in the internet as download:

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are available in the Internet:

www.uhing.com

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